

Wireless Futures Research Connected Aerial Vehicles and Machine Learning for Communications

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Situation Aware Vehicular Engineering Systems

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TEXAS
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Connected Aerial Vehicles

Slides developed by Dr. Nuria Gonzalez Prelcic



Big numbers for the commercial drone industry

82.1 billion



2025

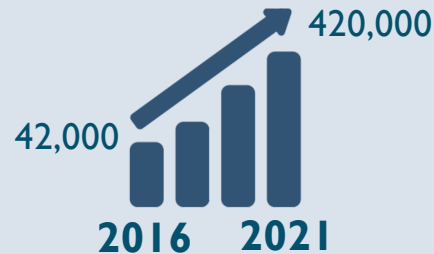


Jobs by 2025
100,000

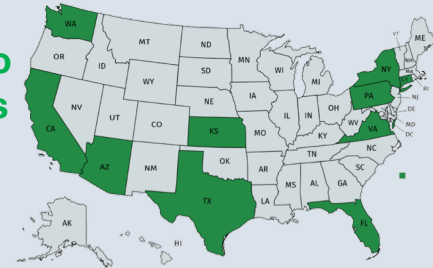
Tax revenue 2015-2025
\$482 million



Commercial
drone fleet



States predicted to
see the most gains
in terms of job
creation and
additional revenue



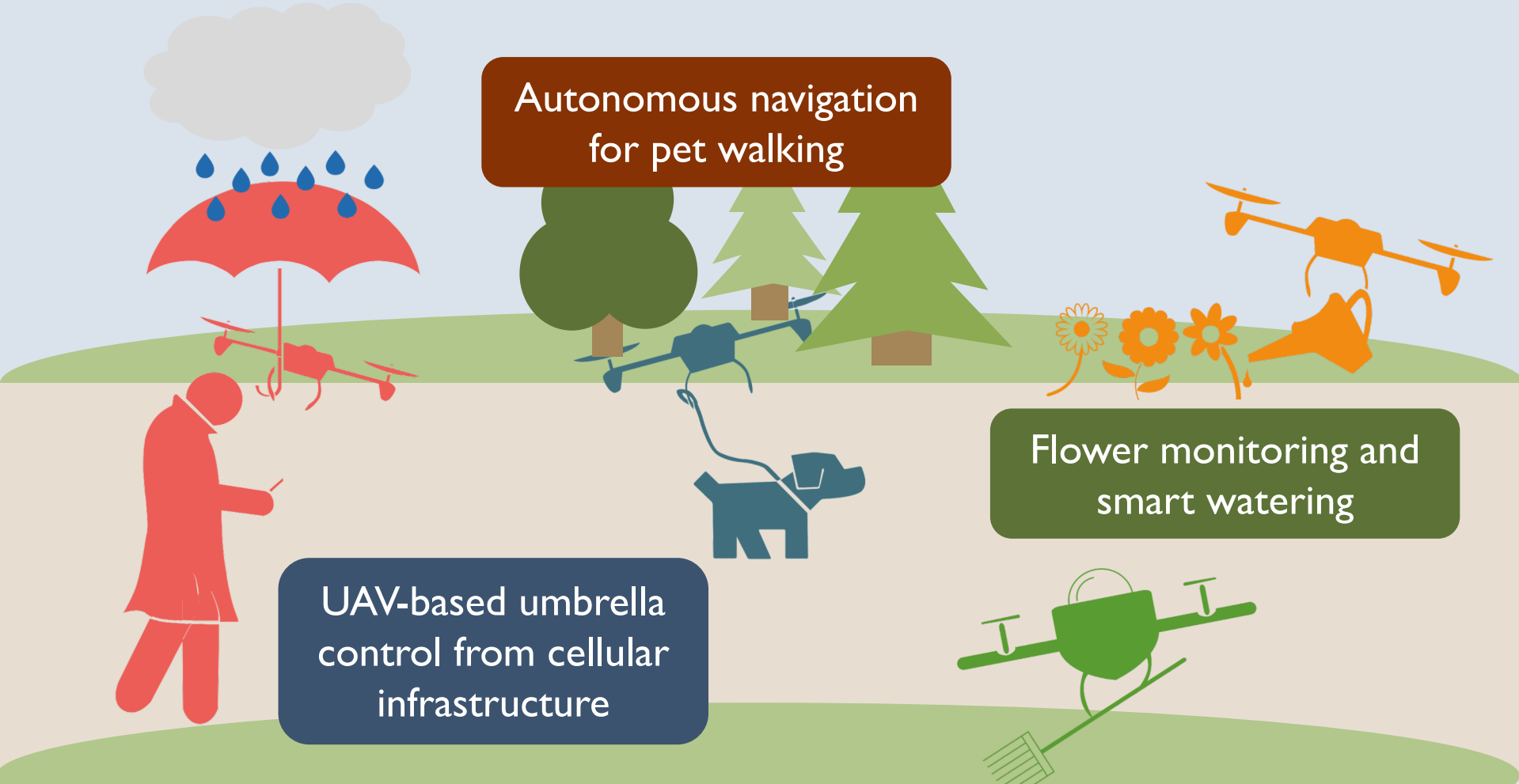
The estimated economic impact of the drone industry is enormous

Disruptive application areas

Autonomous navigation
for pet walking

Flower monitoring and
smart watering

UAV-based umbrella
control from cellular
infrastructure



UAVs as imaging sensors

Real state
marketing*



Panoramic VR
streaming of live video



Professional
photography
(news coverage,
events, ...)

Consumer
photography



Footage is directly used; role for wireless is control and/or live streaming

UAVs for sensing and monitoring

Agriculture (growth and health monitoring, plantation estimation)



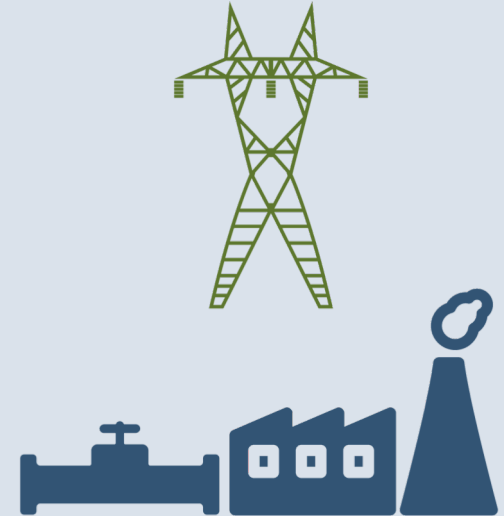
Forestry (species identification, deforestation monitoring)



Traffic monitoring



Powerline/pipeline monitoring



UAVs collect pictures or videos which are later processed

Transportation/delivery

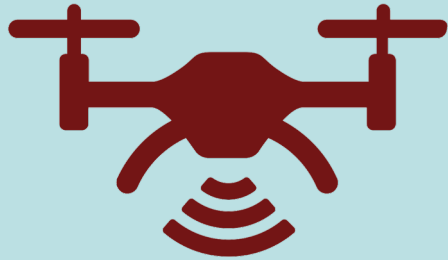


Package/letter/food
delivery



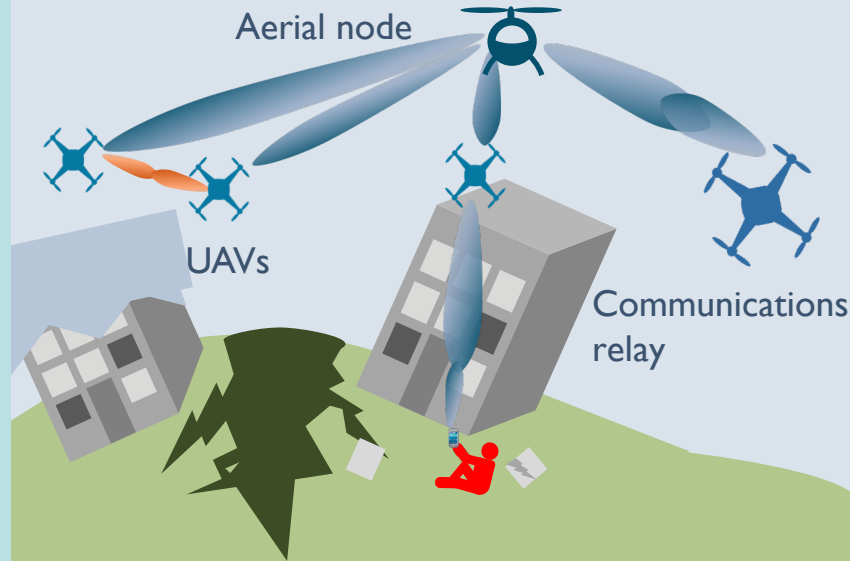
UAVs as transportation vehicles

Mobile hotspot for
crowds

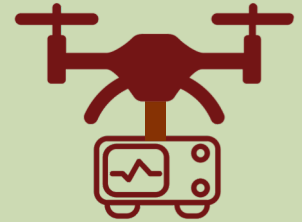


UAVs for wireless

Wireless access
in disaster areas



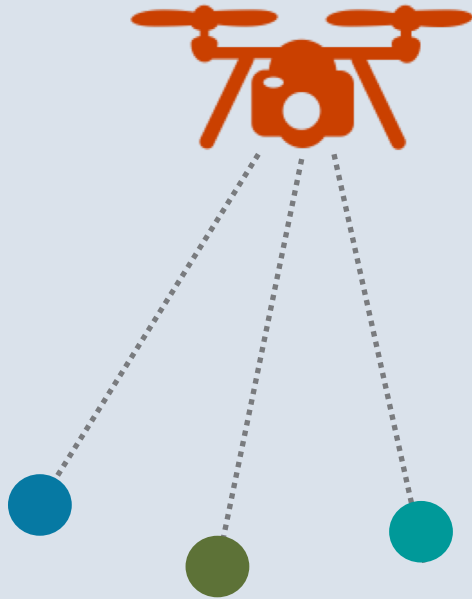
Drive testing
(cellular coverage)



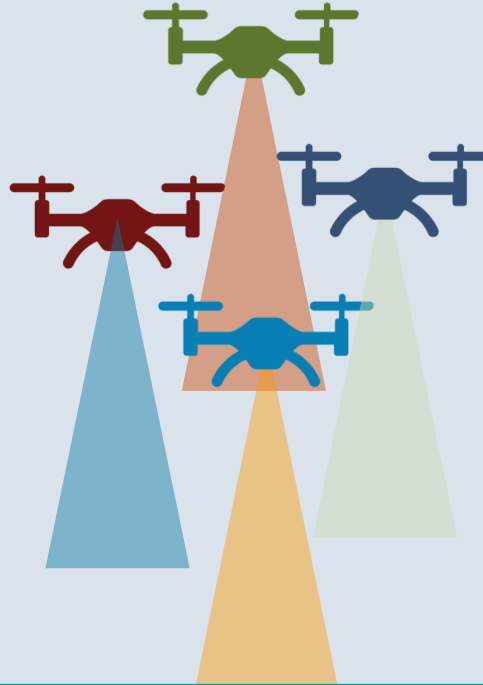
UAVs also enable disruptive applications for communications

Technologies for disruptive UAV applications

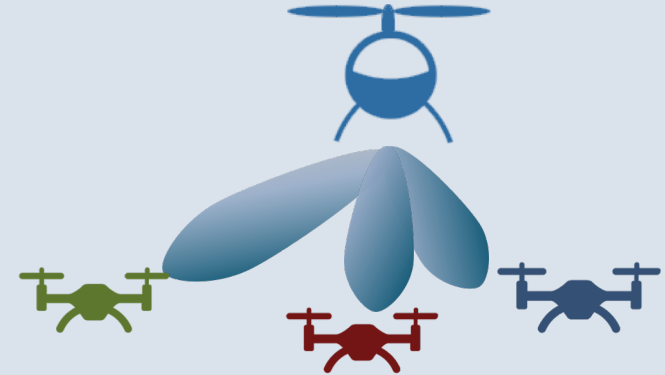
Positioning/mapping/
navigation



Collaborative
sensing



MIMO
communication



SAVES faculties are well positioned on key UAV technologies

Machine learning for communications

Thanks to Yuyang Wang, Monica Ribero, Vutha Va, and Aldebaro Klautau for providing content for this section.

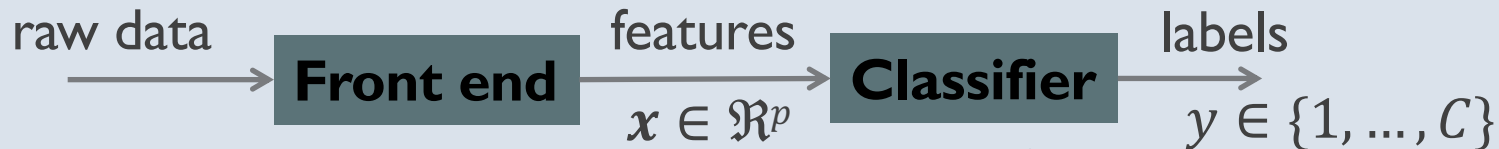
Supported in part by the U.S. DOT Tier I University Transportation Center D-STOP and by TX-DOT under Project 0-6877 CAR-STOP, a gift from TOYOTA ITC, and by a gift from Huawei.



Machine learning for classification

Supervised learning

Given labeled data, devise rule for predicting the label for new data



Shallow learning uses expert knowledge and experiments to reduce dimensionality, deep approach may skip this step

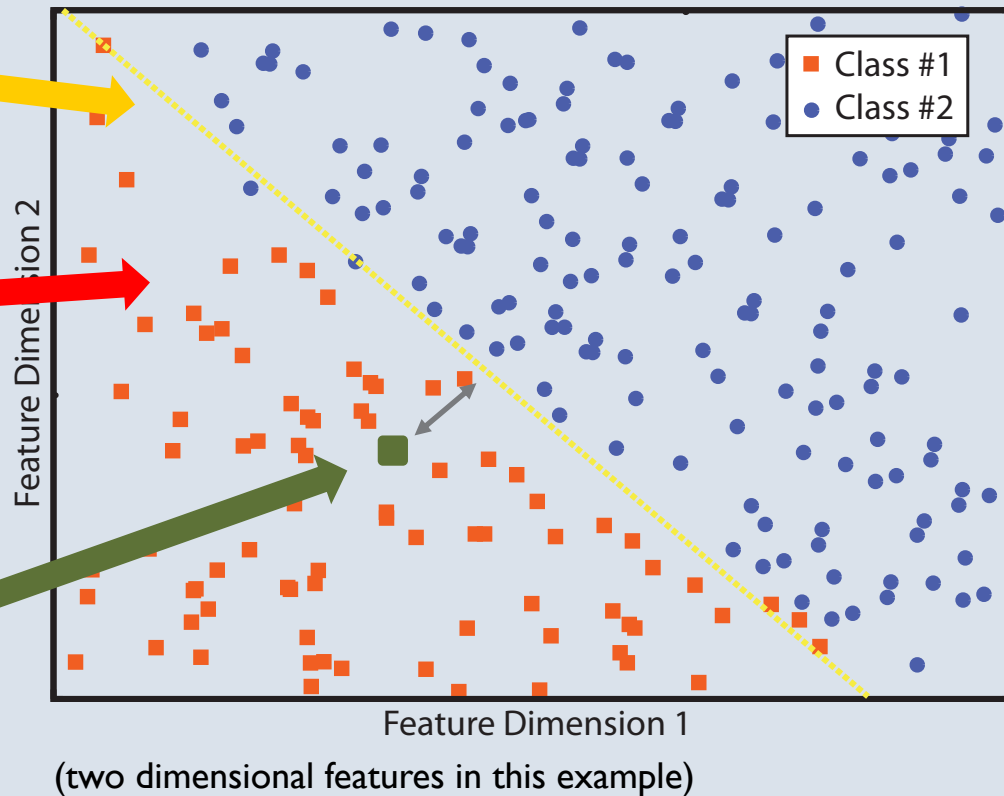
Trained based on past performance data, e.g. feature / label pairs

Machine learning for classification

Machine learning algorithm
devises rule to separate classes

Labeled data
from two classes

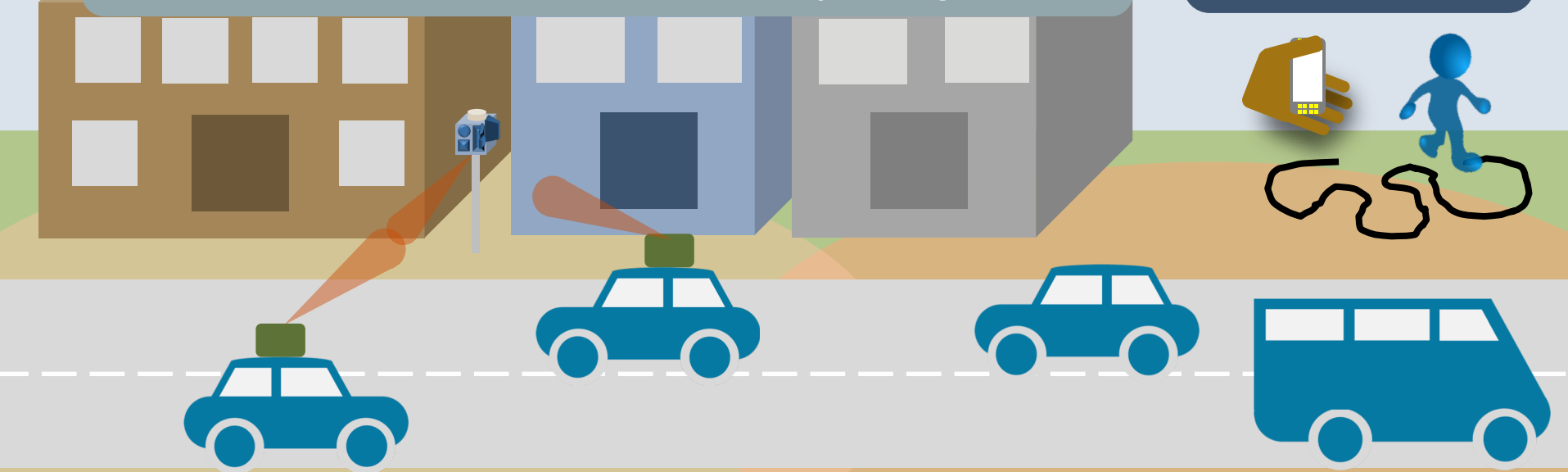
New point is
compared with the
boundary curve to
identify its class



Vehicular applications of millimeter wave

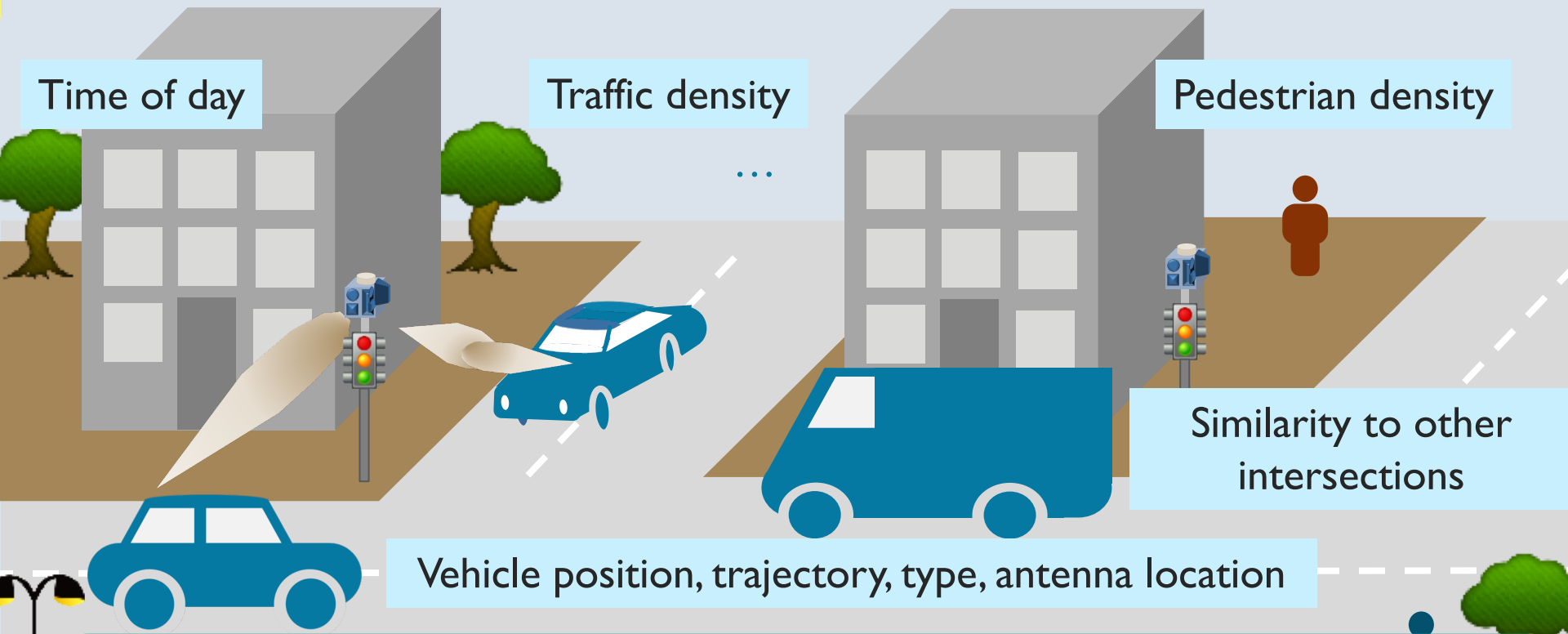
Millimeter wave essential for raw data sharing, situational awareness and internet access for passengers

Irregular motion of user with phone is hard to exploit



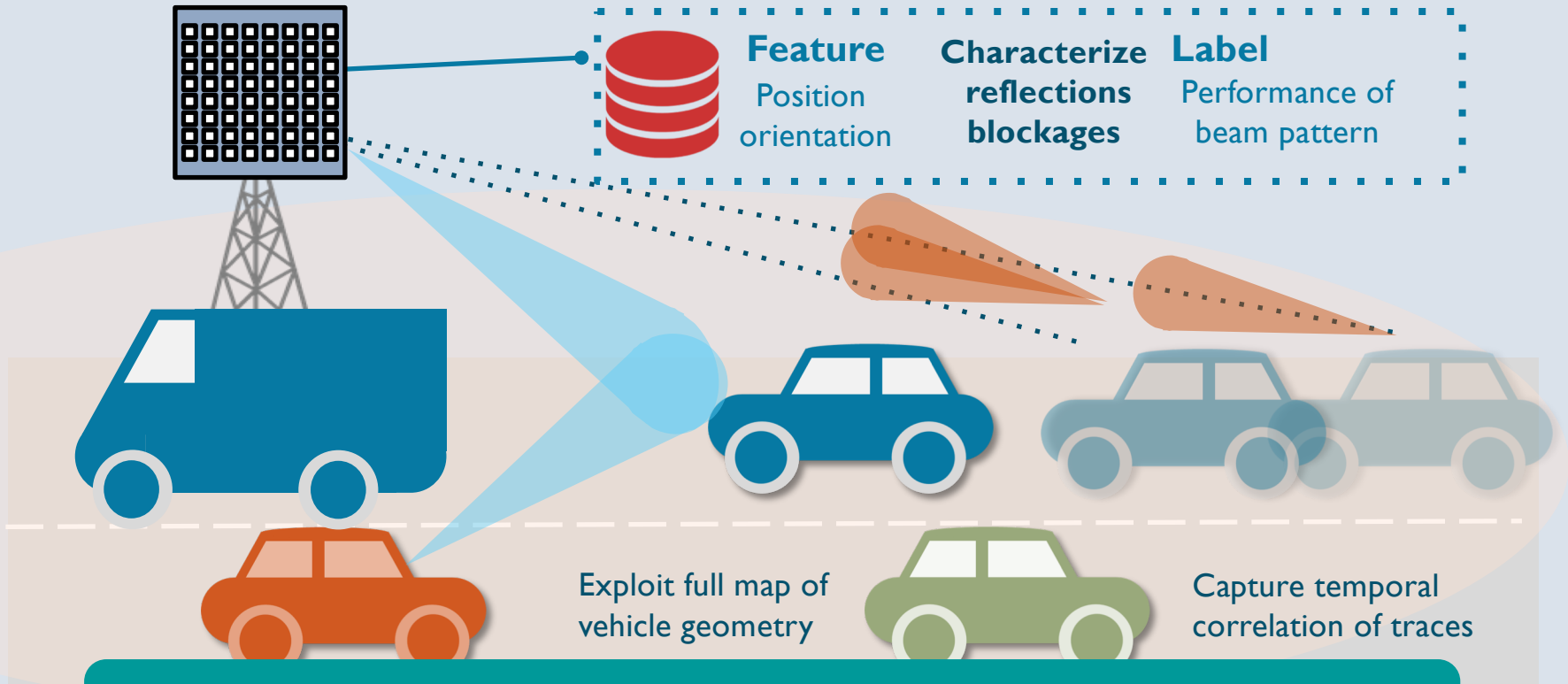
Lanes, consistent antenna placement, similar size cars, and typical gaps, give some regularity to the type of motion in a V2X setting

Side information exploitation opportunities



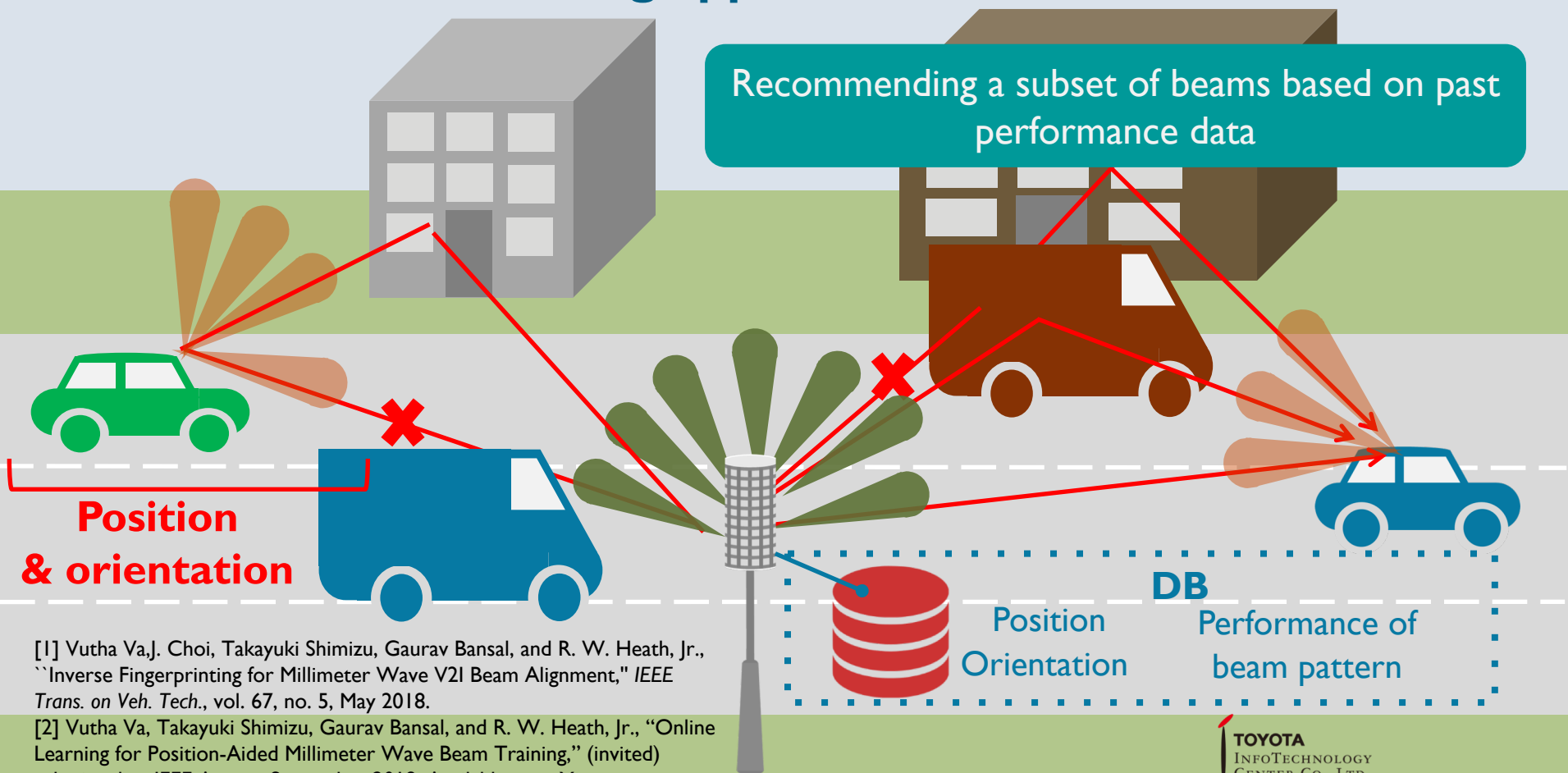
Car position information, time of day, traffic density, pedestrian density, and other data can be leveraged by machine learning algorithms

Machine learning is a tool to exploit structure



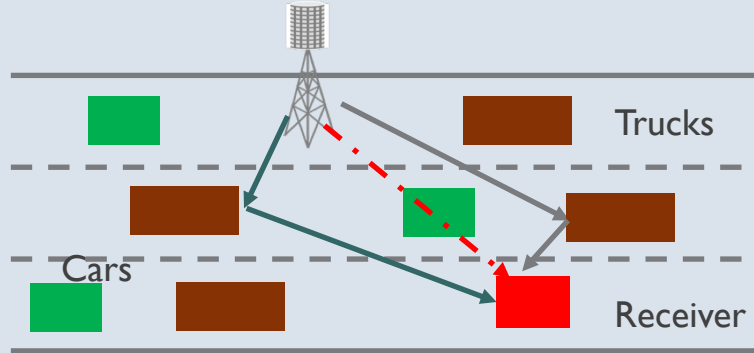
ML is a good framework to exploit correlations between large sets of data with different kinds of entries

Machine learning approach based on location

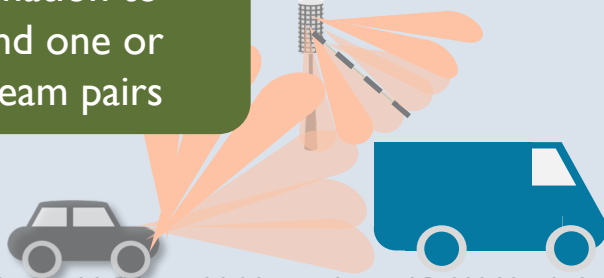


MmWave V2X with full situational awareness

Use knowledge of the receiver and the surrounding vehicle sizes / locations



Use information to recommend one or multiple beam pairs



Ordered vehicles based on **type** and **location**

First lane vehicles
Trucks with larger size
Vehicles closer to the RX



Have larger impacts
on reflections
& beam selection

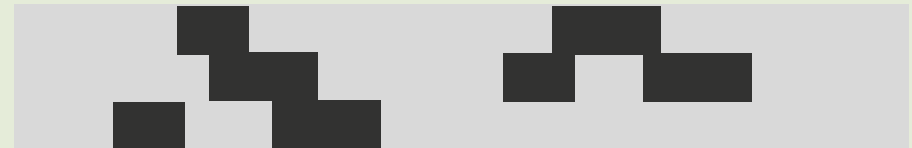
$$\mathbf{v} = [\mathbf{r}, \mathbf{t}_1, \mathbf{t}_2, \mathbf{c}_1, \mathbf{c}_2]$$

Location of RSU

1st & 2nd lane trucks

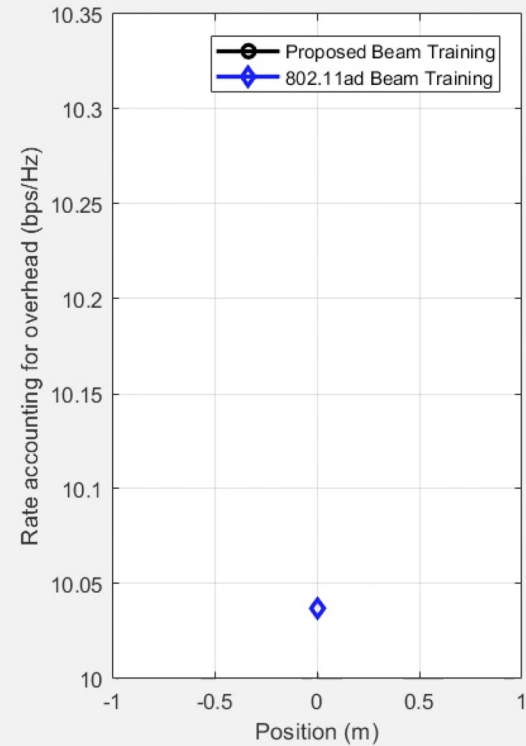
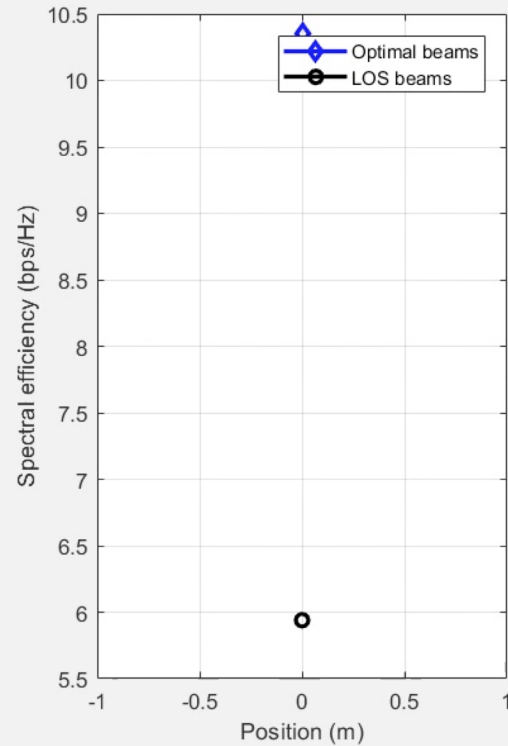
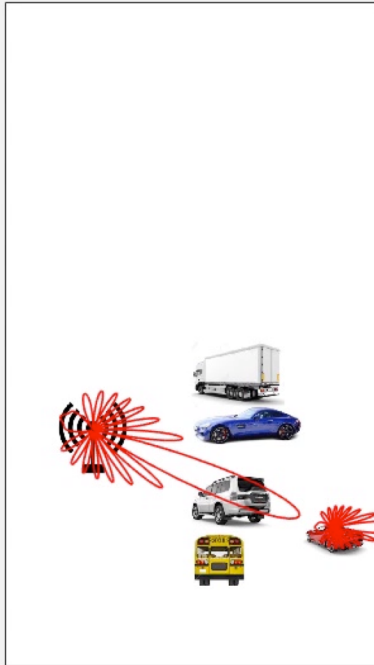
1st & 2nd lane cars

Situational awareness as occupancy image



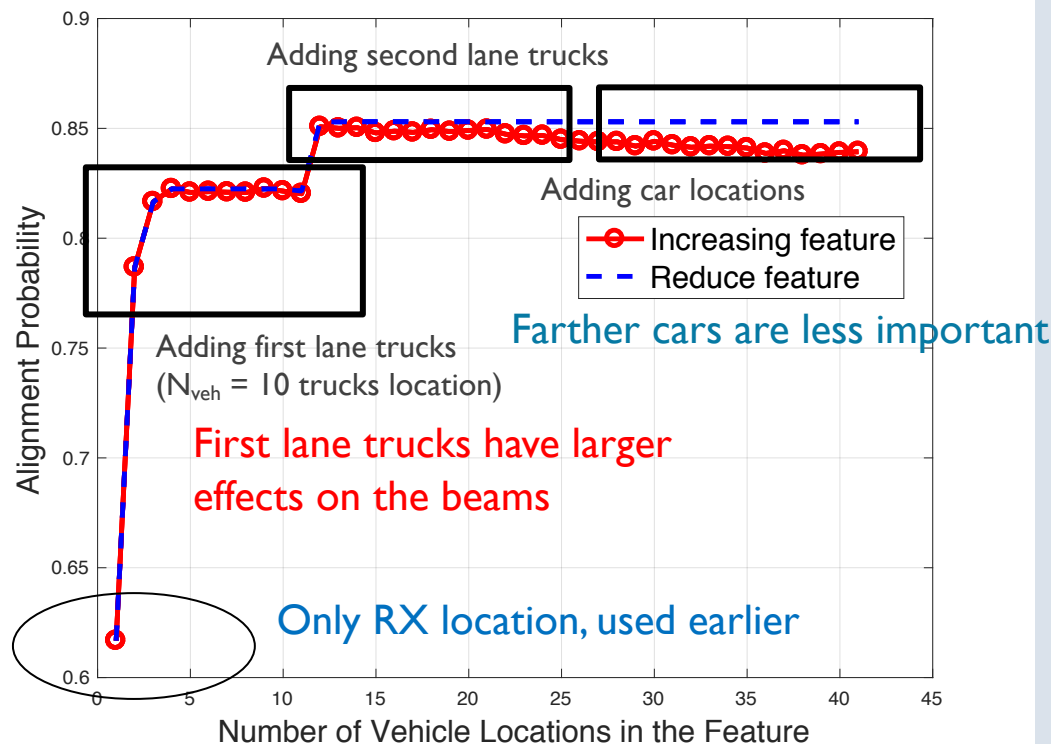
Pixels correspond to road space occupied by cars

Spectral efficiency and overhead



Performance example

Alignment probability



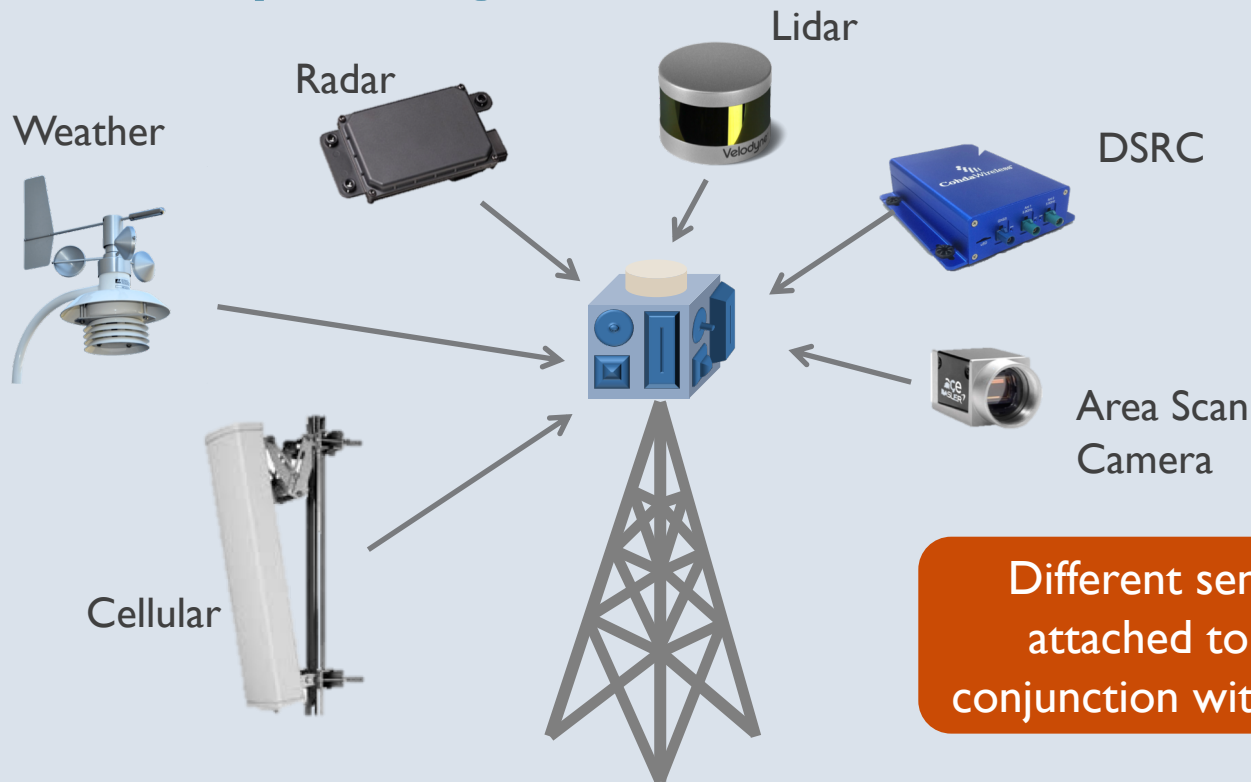
Rate example

Achievable Data rate (bps/Hz)	LOS samples	NLOS samples
LOS beamforming	1.588	0.094
Optimal beam pair	4.183	1.784

LOS beamforming when there are NLOS multi-paths may fail

A concise set of vehicle location can largely improve beam prediction

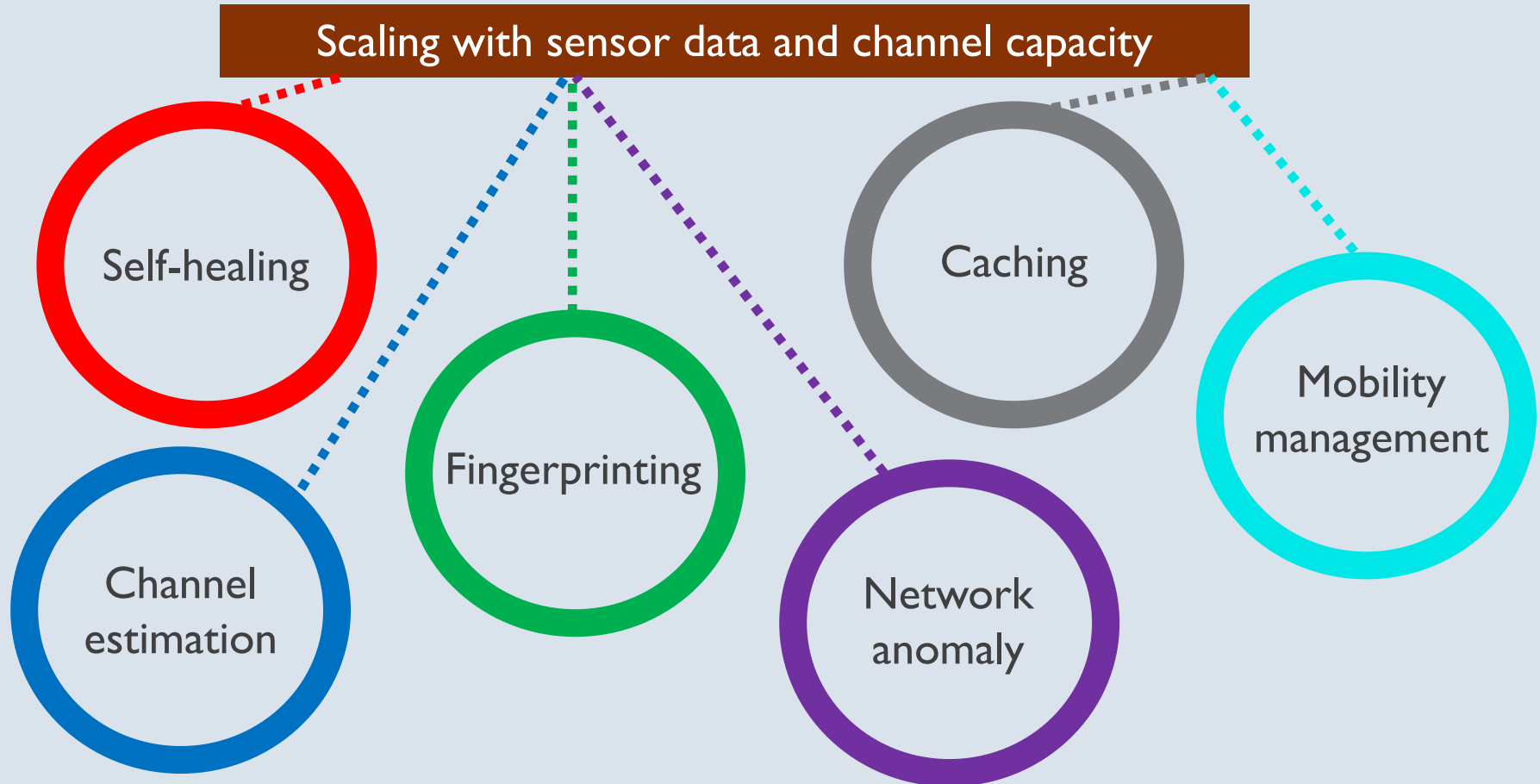
Incorporating other forms of side information



Different sensors can be attached to a tower in conjunction with the antennas

ML can help exploit sensor information to aid communication

Other applications of machine learning in communications



Thank you!



Deep machine learning

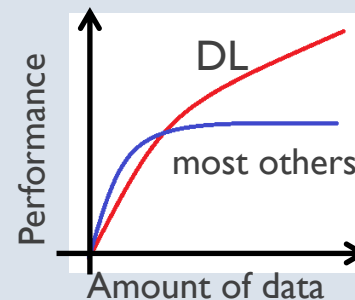
DL key characteristics:

Performance scales with amount of data

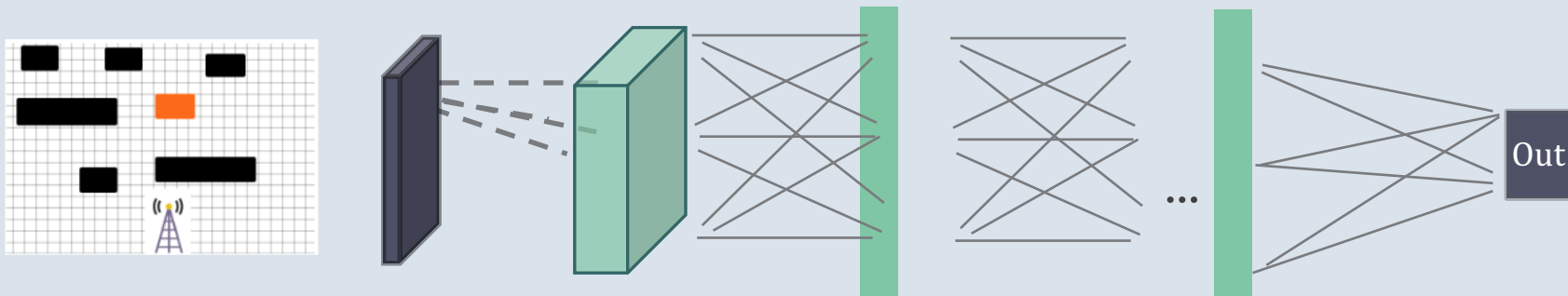
Leverages on stochastic gradient descent (robustness, etc.)

Efficient for supervised, unsupervised, reinforcement and new learning paradigms such as GANs

May not require much feature engineering (e.g. conv nets can learn internal representations)



“raw”
data



[1] Deep Learning-based Channel Estimation for Beamspace mmWave Massive MIMO Systems, H. He, C.-K. Wen, S. Jin, and G. Y. Li, 2018.

[2] Improving Massive MIMO Belief Propagation Detector with Deep Neural Network, X. Tan, W. Xu, Y. Be'ery, Z. Zhang, X. You, and C. Zhang, 2018